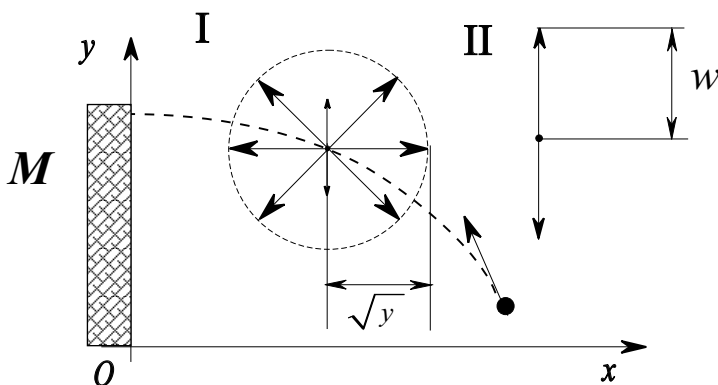


Our statement of the problem



Dynamical system:

$$\dot{x} = \sqrt{y} u_1$$

$$\dot{y} = \sqrt{y} u_2 + v$$

Game space:

$$N = \{(x, y) \in \mathbb{R}^2 : x \geq 0, y \geq 0\}$$

Admissible controls:

$$u = (u_1, u_2) \in P = \text{circle of radius 1}$$

$$v \in Q = \{v \in \mathbb{R}^1 : |v| \leq w\}$$

Terminal set: $M = [-d, 0] \times [0, h]$

I : $t_f \rightarrow \min$

II : $t_f \rightarrow \max$

Isaacs-Bellman equation: $\min_{u \in P} \max_{v \in Q} \{T_x \dot{x} + T_y \dot{y}\} = -1$

For our case: $-\sqrt{y} \rho + w |T_y| + 1 = 0 \quad \rho = \sqrt{T_x^2 + T_y^2}$